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# Nonunity gain minimal-disturbance measurement

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We propose and experimentally demonstrate an optimal nonunity gain Gaussian scheme for partial measurement of an unknown coherent state that causes minimal disturbance of the state. The information gain and the state disturbance are quantified by the noise added to the measurement outcomes and to the output state, respectively. We derive the optimal trade-off relation between the two noises and we show that the tradeoff is saturated by nonunity gain teleportation. Optimal partial measurement is demonstrated experimentally using a linear optics scheme with feedforward.

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## I. INTRODUCTION

One of the most counterintuitive concepts of quantum mechanics is the fact that any attempt to gain information on an unknown quantum state of a physical system will inevitably result in a noisy feedback to the measured system. No matter how cleverly the measurement is performed, the state will always be disturbed to some extent: The more information obtained about a quantum state from a measurement, the more it will be altered, and vice versa. Although this measurement-disturbance concept is very old and originally only of fundamental interest, it has recently received renewed interest due to its direct application in the flourishing field of quantum information science, and in particular, quantum key distribution.

The study of the interplay between the quality of the estimation of a quantum state and the disturbance of the post-measurement state has been extensively carried out in finite-dimensional systems, where optimal trade-off relations have been established for various cases [1–8] and realized recently in an experiment [9]. In contrast, much less effort has been devoted to the study of this tradeoff in infinitely dimensional systems [10–13] where quantum information is carried by observables with a continuous spectrum, important examples being the canonically conjugate quadrature amplitudes. Gaussian states which belong to continuous variable states have played a key role in various experimental realizations of quantum information protocols, thanks to the ease in generating and handling them in a quantum optics laboratory [14,15]. In the Gaussian scenario, full control of the tradeoff between the quality of measurement and state disturbance was recently demonstrated for coherent states using a simple scheme relying solely on linear optics and homodyne detection and near optimal performance was reported [10].

Let us define the problem that will be addressed in this paper. The task is to perform a minimal-disturbance measurement on a coherent state, which is taken from an unknown distribution (see Fig. 1). That is, a completely random coherent state will be received by our measurement device. The question that will be raised and answered in this paper

is: What is the optimal information disturbance tradeoff for this scenario? The answer to that question depends on the figure of merit used to quantify the information gain and the measurement disturbance. For Gaussian states, a useful and practical measure of the quality of the measurement is the phase insensitive added noise [16], since it directly determines the Shannon information optimally extracted by the measurement. Thus the optimal tradeoff between the added noises determines the maximal information that can be gained from the Gaussian measurement represented by a channel with a given additive noise. A second parameter of high relevance for describing the measurement is the gain (attenuation or amplification) of the channel, since the minimization of the added noise is done with respect to that gain. For example, in the previous experiment on minimal-disturbance measurement [10], the added noise was minimized under the constraint that the channel gain was unity (corresponding to a conservation of the mean values). For Gaussian measurements and Gaussian channels this optimization procedure corresponds to a maximization of the fidelity over all possible input states drawn from the unknown coherent state alphabet. It should, however, be noted that by using the fidelity as a measure the optimal solution is non-Gaussian [11] due to specific properties of fidelity.

In this paper we investigate theoretically and experimentally the optimal trade-off relations in terms of added noises using two different strategies. In the first approach the channel gain is a free parameter that is optimized to minimize the tradeoff between the added noises associated with the measurement and disturbance. This trade-off relation was derived by Ralph [17] who also found that the relation could be experimentally demonstrated employing an ideal teleportation scheme with tunable entanglement. Here we propose and experimentally realize a different approach, which is not relying on entanglement but solely on linear optics, Gaussian measurements, and feedforward similar to the one employed in Ref. [10].

In the second approach, which will be carefully addressed in this paper, the channel gain of the minimal-disturbance measurement is fixed to a certain value associated with a particular realization (the unity gain operation demonstrated

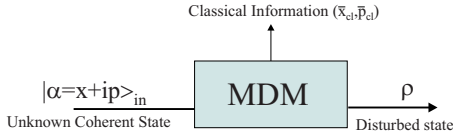


FIG. 1. (Color online) The principles of a minimal-disturbance measurement of coherent states. The input state is drawn from an unknown distribution of coherent states, say  $|\alpha\rangle_{\text{in}} = |x + ip\rangle_{\text{in}}$ , and the task is to acquire information about the state (through a measurement) in such a way that the state is minimally disturbed according to quantum mechanics. This is the essence of a minimal-disturbance measurement. There are two outputs of the protocol: a classical one yielding information about the input state (in the form of two numbers, say  $\bar{x}_{\text{cl}}$  and  $\bar{p}_{\text{cl}}$ ) and a quantum one, namely, the postmeasurement state  $\rho$ . In this paper we consider only cases where the classical data as well as the disturbed quantum state are inflicted by additive phase-insensitive Gaussian noise. The gain  $g$  of the protocol is defined by the ratio between the input and output mean values:  $g = \text{Tr}(x\rho)/\langle\alpha_{\text{in}}|x|\alpha_{\text{in}}\rangle = \text{Tr}(p\rho)/\langle\alpha_{\text{in}}|p|\alpha_{\text{in}}\rangle$ .

in Ref. [10], being a special case). For this case we derive a trade-off relation for arbitrary gains and prove its optimality using two different complementary proofs. As in the previous case, we also find here that a scheme similar to the one in Ref. [10] can be used to implement the optimal tradeoff for fixed but nonunity gain operation. This is demonstrated and near optimal performance is achieved. The experimental scheme is not only of fundamental interest but it can be also applied to perform optimal individual Gaussian attacks in a continuous-variable quantum key distribution scheme based on heterodyne detection [18,19].

The paper is organized as follows. Section II deals in general with tradeoff between added noises and in Sec. III the tradeoff is exemplified by the nonunity gain teleportation scheme. In Sec. IV we give two different proofs of optimality of the tradeoff. Section V is dedicated to the linear optical scheme saturating the tradeoff. The experimental demonstration of the scheme is given in Sec. VI. In Sec. VII we discuss the possibility of using the minimal-disturbance measurement as an eavesdropping attack, and finally, we conclude the paper.

## II. GAUSSIAN MINIMAL-DISTURBANCE MEASUREMENTS

We consider Gaussian quantum operation that acts on a single mode of an optical field “in” described by the canonically conjugate amplitude and phase quadratures  $x_{\text{in}}$  and  $p_{\text{in}}$  ( $[x_{\text{in}}, p_{\text{in}}] = 2i$ ). We assume that the output mode of the operation is characterized by a pair of quadratures  $x_{\text{out}}, p_{\text{out}}$  ( $[x_{\text{out}}, p_{\text{out}}] = 2i$ ) related to the input quadratures by the formulas

$$x_{\text{out}} = g(x_{\text{in}} + n_{\text{out},x}), \quad p_{\text{out}} = g(p_{\text{in}} + n_{\text{out},p}), \quad (1)$$

where the quantity  $g > 0$  is the gain of the operation. The operators  $n_{\text{out},x}$  and  $n_{\text{out},p}$  are standard operators of noises added to the input state. The operation also outputs a pair of mutually commuting variables  $x_{\text{cl}}$  and  $p_{\text{cl}}$  that depend lin-

early on the input quadratures  $x_{\text{in}}$  and  $p_{\text{in}}$  and that therefore can be used for simultaneous measurement of these quadratures. These variables can be expressed, after a suitable scaling transformation, as

$$x_{\text{cl}} = x_{\text{in}} + n_{\text{cl},x}, \quad p_{\text{cl}} = p_{\text{in}} + n_{\text{cl},p}, \quad (2)$$

and satisfy the commutation rules

$$[x_{\text{cl}}, p_{\text{cl}}] = [x_{\text{out}}, x_{\text{cl}}] = [x_{\text{out}}, p_{\text{cl}}] = [p_{\text{out}}, x_{\text{cl}}] = [p_{\text{out}}, p_{\text{cl}}] = 0. \quad (3)$$

The operators  $n_{\text{cl},x}$  and  $n_{\text{cl},p}$  describe noises added to the outcomes of simultaneous measurement of input quadratures  $x_{\text{in}}$  and  $p_{\text{in}}$  by homodyne detection of the variables  $x_{\text{cl}}$  and  $p_{\text{cl}}$ . Naturally, the operators  $n_{\text{out},x}$  and  $n_{\text{cl},x}$  ( $n_{\text{out},p}$  and  $n_{\text{cl},p}$ ) are independent of the input quadrature  $x_{\text{in}}$  ( $p_{\text{in}}$ ) and hence

$$[n_{\text{out},x}, p_{\text{in}}] = [n_{\text{cl},x}, p_{\text{in}}] = [n_{\text{out},p}, x_{\text{in}}] = [n_{\text{cl},p}, x_{\text{in}}] = 0. \quad (4)$$

In addition, the gains of the operation are assumed to be fixed for all input states, i.e.,  $\langle x_{\text{out}} \rangle / \langle x_{\text{in}} \rangle = \langle p_{\text{out}} \rangle / \langle p_{\text{in}} \rangle = g$ ,  $\langle x_{\text{cl}} \rangle / \langle x_{\text{in}} \rangle = \langle p_{\text{cl}} \rangle / \langle p_{\text{in}} \rangle = 1$ , which implies that

$$[n_{\text{out},x}, x_{\text{in}}] = [n_{\text{out},p}, p_{\text{in}}] = [n_{\text{cl},x}, x_{\text{in}}] = [n_{\text{cl},p}, p_{\text{in}}] = 0. \quad (5)$$

Substituting Eqs. (1) and (2) into the commutation rules  $[x_{\text{out}}, p_{\text{out}}] = 2i$  and Eq. (3) one finds using the latter commutation rules (4) and (5) that the noise operators  $n_{\text{out},x}$ ,  $n_{\text{out},p}$ ,  $n_{\text{cl},x}$ , and  $n_{\text{cl},p}$  must satisfy

$$[n_{\text{out},x}, n_{\text{out},p}] = 2i \frac{(1 - g^2)}{g^2}, \quad [n_{\text{cl},x}, n_{\text{cl},p}] = -2i,$$

$$[n_{\text{out},p}, n_{\text{cl},x}] = [n_{\text{cl},p}, n_{\text{out},x}] = 2i,$$

$$[n_{\text{cl},x}, n_{\text{out},x}] = [n_{\text{cl},p}, n_{\text{out},p}] = 0. \quad (6)$$

The noise operators represent the noise by which the outcomes of the homodyne detections of the variables  $x_{\text{cl}}$  and  $p_{\text{cl}}$  as well as the output state are contaminated. The commutation rules (6) and the Heisenberg uncertainty relations then impose fundamental bounds on the noises that have to be satisfied by any Gaussian operation. Since we are interested in partial measurements on coherent states, it is convenient to quantify the two noises by the following sums:

$$\nu_{\text{out}} \equiv \frac{\langle n_{\text{out},x}^2 \rangle + \langle n_{\text{out},p}^2 \rangle}{2}, \quad \nu_{\text{cl}} \equiv \frac{\langle n_{\text{cl},x}^2 \rangle + \langle n_{\text{cl},p}^2 \rangle}{2}, \quad (7)$$

for which the respective bounds read as

$$\nu_{\text{cl}} \geq 1, \quad \nu_{\text{out}} \geq \frac{|1 - g^2|}{g^2}, \quad \nu_{\text{cl}} \nu_{\text{out}} \geq 1. \quad (8)$$

The use of noises (7) is advantageous since they are a simple function of the added noises  $\langle n_{\text{out},x}^2 \rangle$ ,  $\langle n_{\text{out},p}^2 \rangle$ ,  $\langle n_{\text{cl},x}^2 \rangle$ , and  $\langle n_{\text{cl},p}^2 \rangle$  that can be directly measured experimentally. We shall see that the operations that for a given  $\nu_{\text{cl}}$  and  $g$  minimize  $\nu_{\text{out}}$  add noise symmetrically to the  $x$  and  $p$  quadratures, which means that  $\langle n_{\text{out},x}^2 \rangle = \langle n_{\text{out},p}^2 \rangle$  and  $\langle n_{\text{cl},x}^2 \rangle = \langle n_{\text{cl},p}^2 \rangle$  holds. In this case the quantities  $\nu_{\text{out}}$  and  $\nu_{\text{cl}}$  are exactly the noises added to the input state quadratures and to the measurement out-

comes, respectively. This symmetry and isotropy is a natural feature of optimal partial measurement on coherent states that exhibit the same variances for all quadrature components. The interpretation of noises (7) is particularly simple for symmetric operations with unity gain ( $g=1$ ). In this case the quantity  $\nu_{\text{out}}/2$  coincides with the mean number of thermal photons added by the operation to the input state. The interpretation of the quantity  $\nu_{\text{cl}}$  is a little bit more involved. The classical measurement outcomes  $\bar{x}_{\text{cl}}$  and  $\bar{p}_{\text{cl}}$  obtained when measuring the variables  $x_{\text{cl}}$  and  $p_{\text{cl}}$  can be used to prepare a classical guess  $|\alpha_{\text{cl}}\rangle = |(\bar{x}_{\text{cl}} + i\bar{p}_{\text{cl}})/2\rangle$  of the input coherent state  $|\alpha\rangle = |(x+ip)/2\rangle_{\text{in}}$ . By repeating this procedure many times with the same input state we thus prepare on average a mixed quantum state called the estimated state of the input state. Similarly, as in the previous case for the symmetric unity gain operation the quantity  $(\nu_{\text{cl}}+1)/2$  is equal to the mean number of thermal photons in the estimated state.

### III. QUANTUM TELEPORTATION AS A MINIMAL-DISTURBANCE MEASUREMENT

In the following we show that one of the most celebrated quantum information protocols—quantum teleportation—enables a minimal-disturbance measurement in the sense of saturating the inequalities in Eq. (8). Using teleportation as an example we arrive at a very useful equality defining the optimum tradeoff. The optimality will then be rigorously proven in the following two sections.

The protocol in question is the standard continuous variable teleportation scheme [20–22] operating in the nonunity gain regime [23]. An unknown state of an optical mode “in” described by the quadratures  $x_{\text{in}}$  and  $p_{\text{in}}$  is teleported by a sender Alice (A) to a receiver Bob (B). At the beginning, Alice and Bob share an entangled state of two other modes A and B produced by the two-mode squeezing transformation of two vacuum states

$$\begin{aligned} x_A &= \cosh(r)x_A^{(0)} - \sinh(r)x_B^{(0)}, \\ p_A &= \cosh(r)p_A^{(0)} + \sinh(r)p_B^{(0)}, \\ x_B &= \cosh(r)x_B^{(0)} - \sinh(r)x_A^{(0)}, \\ p_B &= \cosh(r)p_B^{(0)} + \sinh(r)p_A^{(0)}, \end{aligned} \quad (9)$$

where  $x_A^{(0)}$ ,  $p_A^{(0)}$ ,  $x_B^{(0)}$ , and  $p_B^{(0)}$  denote the vacuum quadratures of modes A and B and  $r$  is the squeezing parameter. Alice then mixes the input mode with mode A on a balanced beam splitter and performs homodyne detection of the variables  $x_1 = (x_{\text{in}} + x_A)/\sqrt{2}$  and  $p_2 = (p_{\text{in}} - p_A)/\sqrt{2}$  at the outputs of the beam splitter. She then communicates the measurement outcomes  $\bar{x}_1$  and  $\bar{p}_2$  via a classical channel to Bob who displaces his part of the shared state as  $x_B \rightarrow x_{\text{out}} = x_B + g\sqrt{2}\bar{x}_1$  and  $p_B \rightarrow p_{\text{out}} = p_B + g\sqrt{2}\bar{p}_2$ , where  $g > 0$  stands for the gain of the transformation from photocurrents to the output optical field. At Bob's site we thus have the output quadratures (1), where

$$n_{\text{out},x} = x_A + \frac{x_B}{g}, \quad n_{\text{out},p} = -p_A + \frac{p_B}{g}. \quad (10)$$

At Alice's location we have two commuting variables (2) obtained by rescaling of the variables  $x_1$  and  $p_2$  by the factor of  $\sqrt{2}$  and the operators of added noises  $n_{\text{cl},x}$  and  $n_{\text{cl},p}$  read as

$$n_{\text{cl},x} = x_A, \quad n_{\text{cl},p} = -p_A. \quad (11)$$

Substituting now from Eqs. (10) and (11) the noise operators  $n_{\text{out},x}$ ,  $n_{\text{out},p}$ ,  $n_{\text{cl},x}$ , and  $n_{\text{cl},p}$  in the commutation rules (6) one finds the operators in the nonunity gain teleportation indeed satisfy the commutation algebra (6). Making use of Eqs. (9)–(11) one obtains the noises (7) for the nonunity gain teleportation in the form

$$\nu_{\text{cl}} = \cosh(2r), \quad \nu_{\text{out}} = \frac{(1+g^2)}{g^2} \cosh(2r) - \frac{2}{g} \sinh(2r). \quad (12)$$

It holds that  $\langle n_{\text{out},x}^2 \rangle = \langle n_{\text{out},p}^2 \rangle = \nu_{\text{out}}$  and  $\langle n_{\text{cl},x}^2 \rangle = \langle n_{\text{cl},p}^2 \rangle = \nu_{\text{cl}}$ , hence the added noise is isotropic. Eliminating now the parameter  $r$  from the second Eq. (12) using the first one, one finds the tradeoff between the noises (7) in the nonunity gain teleportation to be

$$g^2 \nu_{\text{out}} = (1+g^2) \nu_{\text{cl}} - 2g\sqrt{\nu_{\text{cl}}^2 - 1}. \quad (13)$$

In the plane of the noises  $\nu_{\text{cl}}$  and  $\nu_{\text{out}}$  the trade-off relation determines a certain quadratic curve that turns out to be a fraction of a hyperbola whose exact shape depends on the gain  $g$ . By changing the squeezing  $r$  one can continuously move along the whole trade-off curve from one extreme point to the other one. In the first extreme point one has  $\nu_{\text{cl}} = 1$ , i.e., the first of inequalities (8) is saturated, while  $\nu_{\text{out}} = (1+g^2)/g^2$  and the point is reached for  $r=0$ . In the second extreme point the noise  $\nu_{\text{out}}$  attains the minimal possible value  $\nu_{\text{out}} = |1-g^2|/g^2$ , i.e., the second of inequalities (8) is saturated, whereas  $\nu_{\text{cl}} = \left| \frac{1+g^2}{1-g^2} \right|$  and the point is reached for  $g > 1$  ( $g < 1$ ) by choosing  $r$  such that  $\coth r = g$  ( $\tanh r = g$ ).

Based on the previous results we arrive at an important property of Gaussian quantum operations described by the transformation rules (1) and (2). Namely, in the plane  $(\nu_{\text{cl}}, \nu_{\text{out}})$  the optimal operations lie in the rectangle defined by the inequalities

$$1 \leq \nu_{\text{cl}} \leq \left| \frac{1+g^2}{1-g^2} \right|, \quad (14)$$

$$\frac{|1-g^2|}{g^2} \leq \nu_{\text{out}} \leq \frac{1+g^2}{g^2}. \quad (15)$$

The left-hand sides of the inequalities follow from the commutation rules (6) and cannot be overcome by any operation. On the other hand, the operations that violate either of the right-hand sides of the inequalities add too much noise and therefore they are suboptimal. This can be shown as follows. Consider a quantum operation for which  $\nu'_{\text{out}} > (1+g^2)/g^2$  ( $\nu'_{\text{cl}} > \left| \frac{1+g^2}{1-g^2} \right|$ ). The inequalities (8) then reveal that at most  $\nu'_{\text{cl}} = 1$  ( $\nu'_{\text{out}} = |1-g^2|/g^2$ ). Then, however, we have a better quantum operation given by the teleportation operating in the



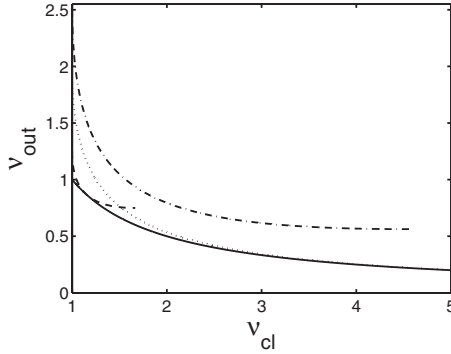


FIG. 2. Optimal tradeoff between the output noise  $\nu_{\text{out}}$  and the noise in measurement outcomes  $\nu_{\text{cl}}$  for a single-mode Gaussian operation with optimal gain  $g = \nu_{\text{cl}} / \sqrt{\nu_{\text{cl}}^2 - 1}$  (solid curve), amplifying operation with  $g = 2$  (dashed curve), unity gain operation with  $g = 1$  (dotted curve), and attenuating operation with  $g = 0.8$  (dash-dotted curve). See the text for details.

first (second) extreme point for which  $\nu_{\text{cl}} = 1$  ( $\nu_{\text{out}} = |1 - g^2|/g^2$ ) but simultaneously  $\nu_{\text{out}} = (1 + g^2)/g^2 < \nu'_{\text{out}}$  ( $\nu_{\text{cl}} = \left| \frac{1+g^2}{1-g^2} \right| < \nu'_{\text{cl}}$ ).

The formulas (13)–(15) are one of the main theoretical results of the present paper. This is because, as we will show in the following section, the tradeoff (13) is optimal on the set of all Gaussian operations described by Eqs. (1), (2), and (6). The tradeoff is depicted for several values of the gain  $g$  in Fig. 2.

Before going to the proof of optimality we can answer another important question based on the tradeoff (13). Up to now we considered Gaussian quantum operations with a fixed gain  $g$ . Provided that the tradeoff (13) is optimal its right-hand side then gives us (after division by  $g^2$ ) the least possible noise  $\nu_{\text{out}}$  that can be attained for a given value of noise  $\nu_{\text{cl}}$  by any such operation. The fundamental question that can be risen in this context is that if the gain  $g$  of operation can be adjusted freely, what is its optimal value  $g_{\text{opt}}$  that gives for a given value of the noise  $\nu_{\text{cl}}$  the least possible value of the noise  $\nu_{\text{out}}$ ? The task was already solved by Ralph [17] who showed that in the nonunity gain teleportation one can adjust for a given value of the noise  $\nu_{\text{cl}}$  the gain such that the third of inequalities (8) is saturated and therefore such teleportation protocol realizes the sought optimal operation. The trade-off relation (13) contains Ralph's result as a particular instance and can be used to rederive it: Expressing  $\nu_{\text{out}}$  as a function of  $g$  and  $\nu_{\text{cl}}$  using Eq. (13) and minimizing it with respect to  $g$  one finds the optimal gain for  $\nu_{\text{cl}} \neq 1$  to be  $g_{\text{opt}} = \nu_{\text{cl}} / \sqrt{\nu_{\text{cl}}^2 - 1}$  that gives  $\nu_{\text{out}} = 1/\nu_{\text{cl}}$  and thus the fundamental quantum mechanical limit given by the third of inequalities (8) is indeed saturated. For  $\nu_{\text{cl}} = 1$  the optimal gain is infinitely large ( $g_{\text{opt}} = \infty$ ) for which one has  $\nu_{\text{out}} = 1$ . In this case, all the inequalities (8) are saturated simultaneously but the operation achieving this regime is unphysical.

#### IV. PROOFS OF OPTIMALITY

In this section we prove the optimality of the inequalities derived above using two different methods. The optimization

task we want to solve can be generally formulated as follows: Find a Gaussian operation described by Eqs. (1), (2), and (6) that for a given gain  $g$  and a given amount of added noise in the measurement outcomes adds the least possible amount of noise into the input state. The optimal operation will in general depend on the quantities used to quantify the two noises. Here we are interested in optimal operations that add noise symmetrically into the amplitude and phase quadrature, i.e., for which  $\langle n_{\text{out},x}^2 \rangle = \langle n_{\text{out},p}^2 \rangle$  and  $\langle n_{\text{cl},x}^2 \rangle = \langle n_{\text{cl},p}^2 \rangle$ . As we will show below, this requirement is satisfied if we take the sums (7) of the variances of the noise operators  $n_{\text{cl},x}$ ,  $n_{\text{cl},p}$ ,  $n_{\text{out},x}$ , and  $n_{\text{out},p}$  to quantify the noise in the measurement outcomes and the noise added into the input state, respectively.

This is a consequence of the fact that for any Gaussian operation that is asymmetric in  $x$  and  $p$  variables, i.e., for which  $\langle n_{\text{out},x}^2 \rangle \neq \langle n_{\text{out},p}^2 \rangle$  and  $\langle n_{\text{cl},x}^2 \rangle \neq \langle n_{\text{cl},p}^2 \rangle$ , there is always a symmetric Gaussian operation giving the same values of  $\nu_{\text{cl}}$  and  $\nu_{\text{out}}$ . This statement can be proved in the following way. Suppose we have the asymmetric operation described by the formulas

$$x_{\text{out}} = g(x_{\text{in}} + n_{\text{out},x}), \quad x_{\text{cl}} = x_{\text{in}} + n_{\text{cl},x},$$

$$p_{\text{out}} = g(p_{\text{in}} + n_{\text{out},p}), \quad p_{\text{cl}} = p_{\text{in}} + n_{\text{cl},p}. \quad (16)$$

Assume that, in addition, we have at our disposal another asymmetric operation that is obtained from the previous one by placing it in between one phase shifter at the input and two phase shifters at the outputs. The first phase shifter interchanges the input quadratures as follows:  $x_{\text{in}} \rightarrow -p_{\text{in}}$  and  $p_{\text{in}} \rightarrow x_{\text{in}}$ , and the two phase shifters on the output modes perform the inverse transformation  $x_i \rightarrow p_i$  and  $p_i \rightarrow -x_i$ ,  $i = \text{out}, \text{cl}$ . Taking all the above transformation rules together the entire operation is described by the following rules:

$$x_{\text{out}} = g(x_{\text{in}} + n'_{\text{out},p}), \quad x_{\text{cl}} = x_{\text{in}} + n'_{\text{cl},p},$$

$$p_{\text{out}} = g(p_{\text{in}} - n'_{\text{out},x}), \quad p_{\text{cl}} = p_{\text{in}} - n'_{\text{cl},x}. \quad (17)$$

The prime was used merely to express that the noise operators in Eq. (17) are completely independent on and therefore completely uncorrelated with the unprimed noise operators in Eq. (16). The variances of the primed and unprimed noise operators are, however, identical,  $\langle n_{\text{out},i}^2 \rangle = \langle (n'_{\text{out},i})^2 \rangle$  and  $\langle n_{\text{cl},i}^2 \rangle = \langle (n'_{\text{cl},i})^2 \rangle$ ,  $i = x, p$ . The desired symmetric operation can then be constructed from the operations (16) and (17) by placing them into two arms of a balanced Mach-Zehnder interferometer. At the first balanced beam splitter of the interferometer the input quadratures are mixed with the quadratures  $x_0$  and  $p_0$  of an auxiliary mode 0 as  $x'_{\text{in}} = (x_{\text{in}} - x_0)/\sqrt{2}$ ,  $p'_{\text{in}} = (p_{\text{in}} - p_0)/\sqrt{2}$  and  $x'_0 = (x_{\text{in}} + x_0)/\sqrt{2}$ ,  $p'_0 = (p_{\text{in}} + p_0)/\sqrt{2}$ . The quadratures  $x'_{\text{in}}, p'_{\text{in}}$  and  $x'_0, p'_0$  are then used as inputs into the operations (16) and (17), respectively. The quadratures at outputs of the operations  $x''_{\text{in}}, p''_{\text{in}}, x''_0$ , and  $p''_0$  are finally superimposed on the second balanced beam splitter of the interferometer at one outcome of which one has

$$x_{\text{out}} = \frac{x''_{\text{in}} + x''_0}{\sqrt{2}} = g(x_{\text{in}} + \tilde{n}_{\text{out},x}),$$

$$p_{\text{out}} = \frac{p''_{\text{in}} + p''_0}{\sqrt{2}} = g(p_{\text{in}} + \tilde{n}_{\text{out},p}), \quad (18)$$

where  $\tilde{n}_{\text{out},x} = (n_{\text{out},x} + n'_{\text{out},p})/\sqrt{2}$  and  $\tilde{n}_{\text{out},p} = (n_{\text{out},p} - n'_{\text{out},x})/\sqrt{2}$ . Further, two pairs of the commuting variables  $x_{\text{cl},\text{in}}, p_{\text{cl},\text{in}}$  and  $x_{\text{cl},0}, p_{\text{cl},0}$  representing the output of the operation (16) on mode “in” of the interferometer and the operation (17) on mode 0, respectively, give after averaging a new pair of commuting variables,

$$x_{\text{cl}} = \frac{x_{\text{cl},\text{in}} + x_{\text{cl},0}}{\sqrt{2}} = x_{\text{in}} + \tilde{n}_{\text{cl},x},$$

$$p_{\text{cl}} = \frac{p_{\text{cl},\text{in}} + p_{\text{cl},0}}{\sqrt{2}} = p_{\text{in}} + \tilde{n}_{\text{cl},p}, \quad (19)$$

where  $\tilde{n}_{\text{cl},x} = (n_{\text{cl},x} + n'_{\text{cl},p})/\sqrt{2}$  and  $\tilde{n}_{\text{cl},p} = (n_{\text{cl},p} - n'_{\text{cl},x})/\sqrt{2}$ . As the primed and the unprimed noise operators are uncorrelated one immediately finds that  $\langle \tilde{n}_{\text{out},x}^2 \rangle = \langle \tilde{n}_{\text{out},p}^2 \rangle$  as well as  $\langle \tilde{n}_{\text{cl},x}^2 \rangle = \langle \tilde{n}_{\text{cl},p}^2 \rangle$  and therefore the new operation described by Eqs. (18) and (19) is symmetric with respect to  $x$  and  $p$ . Moreover, calculating the noises (7) for the new operation yields  $\tilde{\nu}_{\text{out}} = \langle \tilde{n}_{\text{out},x}^2 \rangle = \nu_{\text{out}}$  and  $\tilde{\nu}_{\text{cl}} = \langle \tilde{n}_{\text{cl},x}^2 \rangle = \nu_{\text{cl}}$ , which completes the proof.

### A. Proof I

For the sake of simplicity of mathematical formulas occurring in the proofs of optimality of the tradeoff (13) we will work with rescaled operators of added noises

$$m_{\text{out},x} \equiv g n_{\text{out},x}, \quad m_{\text{out},p} \equiv g n_{\text{out},p}. \quad (20)$$

Using these new operators one can write  $\nu_{\text{out}} = \sigma_{\text{out}}/g^2$ , where

$$\sigma_{\text{out}} \equiv \frac{\langle m_{\text{out},x}^2 \rangle + \langle m_{\text{out},p}^2 \rangle}{2}, \quad (21)$$

and the tradeoff (13) whose optimality is to be proved then reads

$$\sigma_{\text{out}} = (1 + g^2)\nu_{\text{cl}} - 2g\sqrt{\nu_{\text{cl}}^2 - 1}. \quad (22)$$

It is convenient to introduce the column vector  $\tau = (n_{\text{cl},x}, m_{\text{out},x}, n_{\text{cl},p}, m_{\text{out},p})^T$ . In this notation all the commutators (6) can be rewritten in the compact form  $[\tau_i, \tau_j] = 2i\Gamma_{ij}$ , where

$$\Gamma = \begin{pmatrix} 0 & -G \\ G & 0 \end{pmatrix}, \quad G = \begin{pmatrix} 1 & g \\ g & -(1 - g^2) \end{pmatrix}. \quad (23)$$

Since the gains of considered Gaussian operations are fixed the first moments of the noise operators vanish, i.e.,  $\langle \tau \rangle = 0$ , where the symbol  $\langle \rangle$  denotes averaging over the input state  $\rho_{\text{aux}}$  of the auxiliary modes. Consequently, the studied operations are completely characterized by the  $4 \times 4$  real symmetric noise matrix  $N$  with elements  $N_{ij} = \langle \{\tau_i, \tau_j\} \rangle$ , where

$\{A, B\} \equiv (AB + BA)/2$ . The commutation rules (6) then impose a specific uncertainty principle on the noise matrix  $N$  that reads

$$N + i\Gamma \geq 0. \quad (24)$$

Now we want to find such of the considered quantum operations that gives for a given noise  $\nu_{\text{cl}}$  minimum possible noise  $\sigma_{\text{out}}$ . This task can be equivalently reformulated as follows:

$$\min_N f(N) = a\nu_{\text{cl}} + b\sigma_{\text{out}}, \quad (25)$$

under the constraint (24). The coefficients  $a, b \geq 0$  (except for the case  $a=b=0$ ) control the ratio between the noise in the measurement outcomes and in the output state. The optimization task (25) is a typical example of the so-called semidefinite program (SDP) [24]. Recently, also other important problems in quantum information theory were formulated and solved as semidefinite programs ranging from separability criteria [25,26] and optimization of completely positive maps [27] to optimization of teleportation with a mixed entangled state [28] or finding optimal positive operator value measure (POVMs) for quantum state discrimination [29,30].

The SDPs are generally difficult to solve analytically and we are often forced to use numerical methods. However, in the case of the problem (25) we are able to find the solution analytically. This can be done in two steps following the standard strategy employed, for instance, in [27,31]. In the first step we guess the analytical form of the solution of the problem (25) while in the second step we prove its optimality. The first step has been already done in the previous section where we surmised the solution of the problem (25) to be given by the nonunity gain teleportation described by Eqs. (9)–(11). Calculating the operators (20) using Eqs. (10) and substituting them together with the operators (11) into the definition of the noise matrix  $N$  we arrive at the noise matrix for the teleportation in the form

$$N_{\text{tel}} = A \oplus A, \quad (26)$$

where  $A$  is the symmetric  $2 \times 2$  matrix with elements

$$A_{11} = \nu_{\text{cl}}, \quad A_{12} = A_{21} = g\nu_{\text{cl}} - \sqrt{\nu_{\text{cl}}^2 - 1},$$

$$A_{22} = (1 + g^2)\nu_{\text{cl}} - 2g\sqrt{\nu_{\text{cl}}^2 - 1}, \quad (27)$$

where  $\nu_{\text{cl}} = \cosh(2r)$ . Since the matrix (26) is manifestly invariant under the exchange of subscripts  $x$  and  $p$  the noise is added symmetrically into the amplitude and phase quadrature as required and the nonunity gain teleportation is indeed a good candidate for the optimal operation.

In order to prove optimality of the matrix (26) we can proceed along the lines of the proof of optimality of multi-copy asymmetric cloning of coherent states [31]. The proof relies on finding a certain Hermitian positive semidefinite  $4 \times 4$  matrix  $Z$  that satisfies for any admissible matrix  $N$  the condition  $\text{Tr}(ZN) = f(N)$ . From the condition  $Z \geq 0$  and the constraint  $N + i\Gamma \geq 0$  then immediately follows a lower bound on the functional  $f(N)$  that is to be minimized,  $f(N) = \text{Tr}(ZN) \geq -i \text{Tr}(Z\Gamma)$ . If, in addition,  $Z$  satisfies the condition

$$Z(N_{\text{tel}} + i\Gamma) = 0, \quad (28)$$

the lower bound is saturated by the matrix (26) and therefore the corresponding quantum operation is optimal.

The matrix  $Z$  we are looking for can be taken in the block form [31]

$$Z = \frac{1}{2} \begin{pmatrix} P & iQ \\ -iQ & P \end{pmatrix}, \quad (29)$$

where  $P$  and  $Q$  are real symmetric  $2 \times 2$  matrices. The condition (28) gives rise to the following set of equations for the matrices  $P$  and  $Q$ :

$$Q\Gamma = PA, \quad QA = P\Gamma. \quad (30)$$

The matrix  $P$  is determined solely by the condition  $\text{Tr}(ZN) = f(N)$  that gives  $P = \text{diag}(a, b)$ . This is because Eqs. (30) do not impose any further restriction on  $P$  as they provide the equation  $P(A\Gamma^{-1}A - \Gamma) = 0$  for the matrix  $P$  that is satisfied by any  $P$  due to the equality  $A\Gamma^{-1}A = \Gamma$ . Having the matrix  $P$  in hand, one can now substitute it into the equation  $Q = PA\Gamma^{-1}$  derived from the first of Eqs. (30) that leads to the matrix  $Q$  in the form

$$Q = \begin{pmatrix} a(\nu_{\text{cl}} - g\sqrt{\nu_{\text{cl}}^2 - 1}) & a\sqrt{\nu_{\text{cl}}^2 - 1} \\ b[2g\nu_{\text{cl}} - (1 + g^2)\sqrt{\nu_{\text{cl}}^2 - 1}] & b(g\sqrt{\nu_{\text{cl}}^2 - 1} - \nu_{\text{cl}}) \end{pmatrix}. \quad (31)$$

For our guess (26) the coefficients  $a$  and  $b$  are not independent but instead they are tied together by a specific relation that can be calculated by minimizing the functional  $f(N)$  under the constraint (13). Using the standard method of Lagrange multipliers one then finds the relation to be

$$a\sqrt{\nu_{\text{cl}}^2 - 1} = b[2g\nu_{\text{cl}} - (1 + g^2)\sqrt{\nu_{\text{cl}}^2 - 1}], \quad (32)$$

which reveals that the matrix  $Q$  is indeed symmetric. It remains to check the positive semidefiniteness of the matrix (29). Since we require  $a, b \geq 0$  (except for the case  $a = b = 0$ ) the expression in the square brackets on the right-hand side of Eq. (32) must be non-negative. This condition is not satisfied exactly by those operations which violate the inequality  $\nu_{\text{cl}} \leq \left| \frac{1+g^2}{1-g^2} \right|$ . Since, however, these operations have been already ruled out from our considerations as being suboptimal it is sufficient to restrict ourselves to operations satisfying this inequality. For these operations three different cases must be distinguished in dependence on the value of the noise  $\nu_{\text{cl}}$ .

(1) If  $\nu_{\text{cl}} = 1$  then Eq. (32) implies  $b = 0$  whence  $P = Q = \text{diag}(a, 0)$ . The eigenvalues of the matrix  $Z$  then read as  $\alpha_{1,2,3} = 0$  and  $\alpha_4 = a > 0$  and therefore  $Z \geq 0$ .

(2) For  $\nu_{\text{cl}} = \left| \frac{1+g^2}{1-g^2} \right|$  one finds  $a = 0$  using Eq. (32) that gives  $P = \text{diag}(0, b)$  and  $Q = \text{diag}(0, \pm b)$  where the upper (lower) sign holds for  $g > 1$  ( $g < 1$ ). One can again directly calculate the eigenvalues of the matrix  $Z$  in the form  $\beta_{1,2,3} = 0$  and  $\beta_4 = b > 0$  and therefore  $Z \geq 0$ .

(3) In the intermediate case when  $1 < \nu_{\text{cl}} < \left| \frac{1+g^2}{1-g^2} \right|$  one has  $a > 0$  and simultaneously  $b > 0$ . This allows one to introduce the matrix  $V = \sqrt{2} \text{diag}(P^{-1/2}, P^{-1/2})$  and to transform the matrix  $Z$  as

$$Z_1 = V^\dagger Z V = \begin{pmatrix} I & iP^{-1/2}QP^{-1/2} \\ -iP^{-1/2}QP^{-1/2} & I \end{pmatrix}, \quad (33)$$

where  $I$  is the  $2 \times 2$  identity matrix. The specific feature of the transformation (33) is that if  $Z_1$  is positive semidefinite then also  $Z$  is positive semidefinite and it is thus sufficient to prove the positive semidefiniteness of the matrix  $Z_1$ . Performing the similarity transformation  $Z_2 = UZ_1U^\dagger$  where

$$U = \frac{1}{\sqrt{2}} \begin{pmatrix} I & iI \\ iI & I \end{pmatrix}, \quad (34)$$

the matrix  $Z_1$  is brought into the block diagonal matrix  $Z_2 = \text{diag}(I + P^{-1/2}QP^{-1/2}, I - P^{-1/2}QP^{-1/2})$  whose eigenvalues are easy to find in the form  $\gamma_{1,2} = 0$  and  $\gamma_{3,4} = 2$ . Consequently,  $Z_2 \geq 0$  and therefore also  $Z \geq 0$ , which completes the proof.

## B. Proof II

There is an alternative way of proving the optimality of the noise matrix (26). The proof relies on the mapping of the noise operators  $m_{\text{out},x}$ ,  $m_{\text{out},p}$ ,  $n_{\text{cl},x}$ , and  $n_{\text{cl},p}$  onto the quadratures in the nonunity gain teleportation. The search for the optimal noise matrix then boils down to searching a suitable two-mode state shared in the nonunity gain teleportation.

Suppose we have a noise matrix  $N$ , i.e., a real symmetric  $4 \times 4$  matrix satisfying the uncertainty principle  $N + i\Gamma \geq 0$ . Assume in addition, there is a real regular  $4 \times 4$  matrix  $M$  satisfying the condition

$$\Gamma = M\Omega M^T, \quad (35)$$

which means that  $M$  realizes mapping between the commutation rules for noise operators  $[\tau_i, \tau_j] = 2i\Gamma_{ij}$  and the standard canonical commutation rules  $[\xi_i, \xi_j] = 2i\Omega_{ij}$ , where  $\xi = (x_A, p_A, x_B, p_B)^T$  is the vector of quadratures and

$$\Omega = J \oplus J, \quad J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad (36)$$

is the standard symplectic matrix. Provided that such a matrix  $M$  exists we can associate with any admissible noise matrix  $N$  a certain real symmetric  $4 \times 4$  matrix

$$V_{AB} = M^{-1}N(M^T)^{-1}, \quad (37)$$

that can be shown to satisfy the standard Heisenberg uncertainty principle  $V_{AB} + i\Omega \geq 0$  and therefore can be shown to be a covariance matrix of a two-mode state. This can be shown as follows. Expressing the left-hand side of the Heisenberg uncertainty principle using the formulas (35) and (37) one finds  $V_{AB} + i\Omega = M^{-1}(N + i\Gamma)(M^T)^{-1}$ . Taking now the spectral decomposition  $N + i\Gamma = \sum_i \mu_i |\mu_i\rangle\langle\mu_i|$ , where  $\mu_i \geq 0$  are eigenvalues and  $|\mu_i\rangle$  are corresponding eigenvectors of the matrix  $N + i\Gamma$ , one finds that  $\langle\psi|V_{AB} + i\Omega|\psi\rangle = \sum_i \mu_i \langle\psi|M^{-1}|\mu_i\rangle\langle\mu_i| \geq 0$  for any vector  $|\psi\rangle$  and therefore  $V_{AB} + i\Omega$  is indeed positive semidefinite, whence  $V_{AB}$  is a two-mode covariance matrix. Since  $V_{AB}$  is a covariance matrix its elements can be written as  $(V_{AB})_{ij} = \text{Tr}[\rho_{AB}\{\xi_i, \xi_j\}]$ ,  $i, j = 1, \dots, 4$ , where  $\xi_i$ ,  $i = 1, \dots, 4$  are components of the vector  $\xi$  of standard quadratures and  $\rho_{AB}$  is a state of two modes  $A$

and  $B$ . A natural realization of the vector of quadratures  $\xi$  is by the linear relation

$$\xi = M^{-1} \tau. \quad (38)$$

In this case the state  $\rho_{AB}$  coincides with the state  $\rho_{\text{aux}}$  over which the averaging in the definition of the noise matrix  $N$  is performed.

It remains to show that a regular matrix  $M$  satisfying the condition (35) exists. Nonunity gain teleportation provides such a matrix that, in addition, proves to be suitable for minimization of the functional (25). By writing Eqs. (10) and (11) in the matrix form (38) one finds the matrix  $M$  in the nonunity gain teleportation to be a regular matrix of the form

$$M = \begin{pmatrix} 1 & 0 & 0 & 0 \\ g & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & -g & 0 & 1 \end{pmatrix}. \quad (39)$$

The problem of minimization of the functional (25) over the noise matrices  $N$  is then transformed into the problem of finding a two-mode state  $\rho_{AB}$  (with covariance matrix  $V_{AB}$ ) shared in the nonunity gain teleportation that minimizes the functional (25). Substituting from Eqs. (10) and (11) into Eq. (25) using the definitions (7) one can express the functional (25) as the trace  $f(N) = \text{Tr}(\rho_{AB} O)$ , where

$$O = \frac{1}{2} [a(g^2 x_A^2 + 2g\{x_A, x_B\} + x_B^2 + g^2 p_A^2 - 2g\{p_A, p_B\} + p_B^2) + b(x_A^2 + p_A^2)]. \quad (40)$$

The operator  $O$  is lower bounded by  $O \geq \min[\text{eig}(O)]$ , which implies that the functional  $f(N)$  is lower bounded by  $f(N) \geq \min[\text{eig}(O)]$ . This lower bound is saturated if the state  $\rho_{AB}$  is an eigenstate of the operator (40) corresponding to its lowest eigenvalue. The operator (40) can be diagonalized by the two-mode squeezing transformation  $S$  described in the Heisenberg picture by Eq. (9). Choosing the squeezing parameter as

$$\tanh(2r) = \frac{2ga}{a(g^2 + 1) + b}, \quad (41)$$

the operator (40) is diagonalized to the form

$$O' = SOS^\dagger = 2(xn_A + yn_B) + x + y, \quad (42)$$

where  $n_i = (x_i^2 + p_i^2)/4 - 1/2$ ,  $i = A, B$  are standard photon number operators and  $x, y \geq 0$ . Inserting the formula (42) into the expression for  $f(N) = \text{Tr}(\rho_{AB} O)$  one obtains that  $f(N) = \text{Tr}(S\rho_{AB} S^\dagger O')$ , which is obviously minimized if  $S\rho_{AB, \text{opt}} S^\dagger = |00\rangle\langle 00|$ , where  $|00\rangle$  is the vacuum state. Hence, the optimal state  $\rho_{AB, \text{opt}}$  is the two-mode squeezed vacuum state with the squeezing parameter given by the formula (41). Thus, we arrived in a different way at the conclusion that the nonunity gain teleportation with shared two-mode squeezed vacuum state with a properly chosen squeezing represents optimal Gaussian quantum operation that for a given gain  $g$  and noise  $\nu_{\text{cl}}$  introduces the least possible noise  $\nu_{\text{out}}$ .

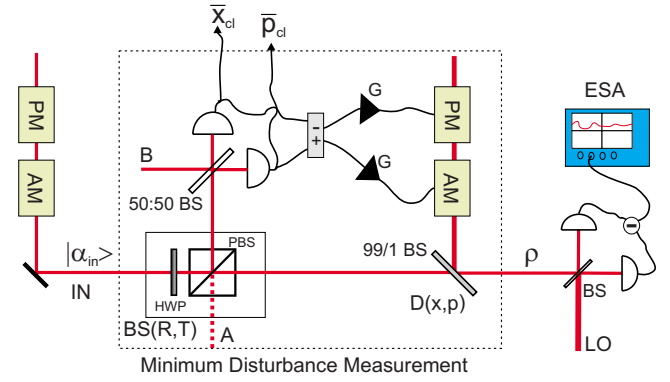


FIG. 3. (Color online) The experimental scheme. AM: Amplitude modulator; PM: Phase modulator;  $|\alpha\rangle$ : The incoming coherent state to be measured; HWP: Half wave plate; PBS: Polarizing beam splitter cube; BS: Beam splitter;  $D(x, p)$ : Displacement operation; B: Auxiliary beam; BS(R, T): Variable beam splitter with reflectivity  $R$  and transmissivity  $T$  for intensity; A: Vacuum mode; G: electronic gains;  $x_{\text{cl}}, p_{\text{cl}}$ : Classical measurement outcomes;  $\rho$ : Output state; LO: Local oscillator beam; ESA: Electronic spectrum analyzer.

## V. LINEAR OPTICS SCHEME

Nonunity gain teleportation is not the only scheme that saturates the optimal tradeoff (13). As shown in Ref. [10], there are at least two other schemes that can accomplish a minimal-disturbance measurement. One other strategy is to use optimal  $1 \rightarrow 2$  Gaussian cloning followed by a joint measurement between one of the clones and the anticlon. However, a much simpler strategy, which will be investigated in the following, achieves the optimal bound using only linear optics, homodyne detection, and feedforward. The setup is depicted in Fig. 3. In this scheme the input mode “in” is mixed with an auxiliary vacuum mode  $A$  on an unbalanced beam splitter with amplitude reflectivity  $\sqrt{R}$  and transmissivity  $\sqrt{T}$  ( $R+T=1$ ). The reflected mode “in” and the transmitted mode  $A$  are described by the following quadratures:

$$\begin{aligned} x'_{\text{in}} &= \sqrt{R}x_{\text{in}} + \sqrt{T}x_A^{(0)}, & p'_{\text{in}} &= \sqrt{R}p_{\text{in}} + \sqrt{T}p_A^{(0)}, \\ x'_A &= \sqrt{T}x_{\text{in}} - \sqrt{R}x_A^{(0)}, & p'_A &= \sqrt{T}p_{\text{in}} - \sqrt{R}p_A^{(0)}. \end{aligned} \quad (43)$$

The mode “in” is then superimposed with another vacuum mode  $B$  on a balanced beam splitter and the quadratures  $x'_1 \equiv x'_{\text{in}} = (x'_{\text{in}} + x_B^{(0)})/\sqrt{2}$  and  $p'_2 \equiv p'_A = (p'_{\text{in}} - p_B^{(0)})/\sqrt{2}$  are measured at its outputs. After rescaling the measured quadratures  $x_1$  and  $p_2$  by the factor  $\sqrt{2}/R$  we arrive at the variables  $x_{\text{cl}}$  and  $p_{\text{cl}}$  in the form (2), where

$$n_{\text{cl}, x} = \frac{\sqrt{T}x_A^{(0)} + x_B^{(0)}}{\sqrt{R}}, \quad n_{\text{cl}, p} = \frac{\sqrt{T}p_A^{(0)} - p_B^{(0)}}{\sqrt{R}}. \quad (44)$$

The outcomes of the measurements  $\bar{x}_1$  and  $\bar{p}_2$  are then used to displace the mode  $A$  as  $x'_A \rightarrow x'_{\text{out}} = x'_A + \sqrt{2G}\bar{x}_1$  and  $p'_A \rightarrow p'_{\text{out}} = p'_A + \sqrt{2G}\bar{p}_2$ , where  $G$  is the normalized electronic gain. The output quadratures  $x_{\text{out}}$  and  $p_{\text{out}}$  are then of the form (1), where the gain reads as



$$g = \sqrt{T} + G\sqrt{R}, \quad (45)$$

and

$$n_{\text{out},x} = \frac{(G\sqrt{T} - \sqrt{R})x_A^{(0)} + Gx_B^{(0)}}{g},$$

$$n_{\text{out},p} = \frac{(G\sqrt{T} - \sqrt{R})p_A^{(0)} - Gp_B^{(0)}}{g}. \quad (46)$$

Inserting now Eqs. (44) and (46) into the definitions (7) one finds

$$\nu_{\text{cl}} = \frac{1+T}{1-T}, \quad \nu_{\text{out}} = \frac{(G\sqrt{T} - \sqrt{R})^2 + G^2}{g^2}. \quad (47)$$

Expressing  $g^2\nu_{\text{out}}$  using the second of Eqs. (47), substituting in the obtained formula for  $G$  employing Eq. (45) and making use of the formula  $R+T=1$  and the first of Eqs. (47), we finally confirm that the noises (47) indeed satisfy the optimal tradeoff (13).

Equations (47) immediately allow us to derive the output noise  $\nu_{\text{out}}$  for the case with optimized gain. Making use of the first of Eqs. (47) in the formula  $g_{\text{opt}} = \nu_{\text{cl}} / \sqrt{\nu_{\text{cl}}^2 - 1}$  one gets the optimal gain

$$g_{\text{opt}} = \frac{1+T}{2\sqrt{T}}. \quad (48)$$

Substituting further the latter expression for  $g_{\text{opt}}$  into Eq. (45) one finds the electronic gain  $G_{g_{\text{opt}}}$  to be  $G_{g_{\text{opt}}} = \sqrt{1-T}/2\sqrt{T}$ . Inserting now Eq. (48) and the obtained expression for  $G_{g_{\text{opt}}}$  into the second of Eqs. (47) we finally arrive at the output noise in the linear optics scheme with the feedforward in the form

$$\nu_{\text{out}} = \frac{1-T}{1+T}. \quad (49)$$

Comparison of the formula for  $\nu_{\text{out}}$  just obtained with the formula for the noise  $\nu_{\text{cl}}$  given in Eq. (47) reveals that  $\nu_{\text{cl}}\nu_{\text{out}}=1$  holds and therefore the third of inequalities (8) is saturated.

## VI. EXPERIMENT

After the theoretical part where we proved the optimality of the scheme depicted in Fig. 3 we now proceed by describing the actual experiments demonstrating minimal-disturbance measurements (MDMs) on coherent states. As mentioned above, a MDM was recently performed on coherent states [10] in which the output signal had the same mean value as the input. The present work extends this previous work to a more complete experimental study of MDMs of coherent states, namely, to the cases where the mean value of the input state is not preserved. We systematically investigated two cases. First, we considered the nonunity gain phase-insensitive MDM where the gain was optimized according to the formula (48). In the second case we studied the nonunity gain MDM where the optical gain was fixed.

The experimental setup is depicted in Fig. 3. In both experiments we used a stable continuous wave Nd:YAG laser from Innolight oscillating at 1064 nm wavelength, which could deliver up to 500 mW of power in one transversal mode. The signal beam, local oscillator (LO) beam, and the auxiliary beam (B) were all obtained from this source enabling high quality mode matching between the beams and hence allowing very efficient quantum measurements. We generated the coherent states by placing concatenated electro-optical phase and amplitude modulators in the beam path. We applied a signal to the modulators at 14.3 MHz, which created sidebands with respect to the laser carrier, meaning that some of the photons from the carrier were transferred to these sidebands. Hence we defined our coherent state to reside at the sideband frequency of 14.3 MHz and having a 100 kHz bandwidth. In this operating window the dark noise of the detectors was negligible and the locking loops for the amplitude and phase quadrature measurement at the homodyne detector were optimized to operate stably. In addition, the feed-forward loop was chosen to function most efficiently inside this window. After the preparation, the coherent state impinges on a beam splitter BS(R,T) with variable beam splitting ratio. The variable beam splitter is realized by placing a polarizing beam splitter behind a half wave plate in the beam path. The reflected part of the input state is mixed with an auxiliary beam of equal intensity on a 50:50 beam splitter. By directly measuring the output of the beam splitter and subsequently constructing the sum and difference photocurrents, the amplitude and phase quadratures of the reflected light are simultaneously measured [32], thus information about the input is acquired. The classical measurement outcome is amplified electronically and fed to another pair of amplitude and phase modulators, which are traversed by another auxiliary beam. This beam is then coupled into the remaining part of the signal beam thus accomplishing a lossless displacement operation. The output state  $\rho$  is finally analyzed by making use of a homodyne detector. A bright local oscillator beam interferes with the signal beam on a beam splitter, and the conjugate quadratures, amplitude and phase, are stably measured by locking the relative phase between the two beams employing standard electronic feedback techniques. The first and second moments of the amplitude and phase quadratures of the output state as well as the input state are thus measured using an electronic spectrum analyzer. The input state was characterized by switching off the displacement operation, measuring the resulting output state, and inferring the input state by carefully characterizing all the losses including the detector and beam splitter losses. In all the measurements the central frequency was 14.3 MHz, the resolution bandwidth was 100 kHz, and the video bandwidth was 30 Hz.

In the first experiment the optical gain of our measurement device depended on the transmission of the beam splitter BS(R,T) according to Eq. (48) thereby reducing the noise  $\nu_{\text{out}}$  to a minimum possible value. This was achieved by tuning the variable beam splitter to various transmission-to-reflection ratios and correspondingly adjusting the feed-forward electronic gain to obtain the desired optimal optical gain.

In order to quantify our measurement device and to verify that it indeed measures the coherent state optimally with

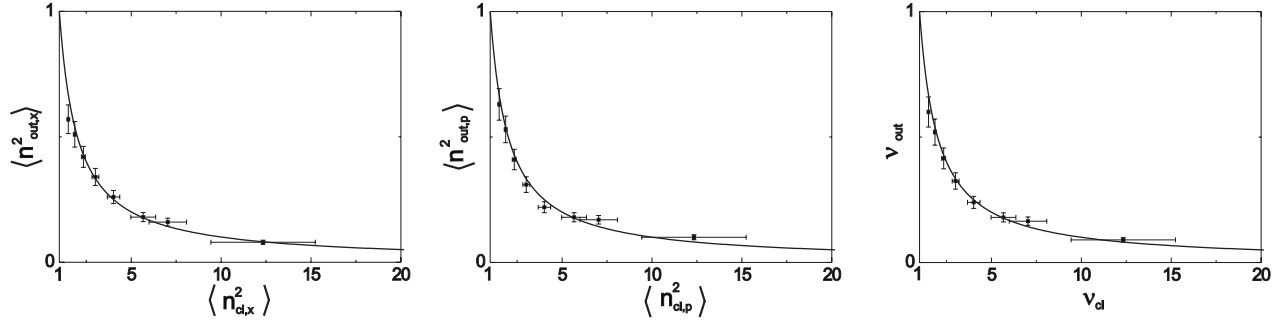


FIG. 4. Experimental results for MDM with optimized gain. Variances  $\langle n_{\text{out},x}^2 \rangle$  (left figure) and  $\langle n_{\text{out},p}^2 \rangle$  (middle figure) of the added noises in the amplitude and phase quadratures are plotted against the quantity  $\langle n_{\text{cl},x}^2 \rangle$  and  $\langle n_{\text{cl},p}^2 \rangle$  characterizing the noise added into the outcomes of simultaneous measurement of amplitude and phase quadratures. We also make use of Eq. (7) to plot  $\nu_{\text{out}}$  against  $\nu_{\text{cl}}$  (right figure). The solid line represents the theoretical relation  $\nu_{\text{out}} = 1/\nu_{\text{cl}}$ . The experimental data were obtained by taking into account the detection efficiency of 83% at the homodyne detector. The error bars in the x-axis stem from the uncertainty in the measurement of the beam splitter transmittance (2% deviation). The error bars in the y axis are caused by 0.1 dB relative measurement accuracy of the electronic spectrum analyzer and 0.1 dB deviation of the homodyning efficiency.

minimal disturbance we needed to determine the added noises  $\langle n_{\text{out},x}^2 \rangle$ ,  $\langle n_{\text{out},p}^2 \rangle$ ,  $\langle n_{\text{cl},x}^2 \rangle$ , and  $\langle n_{\text{cl},p}^2 \rangle$ . For this purpose we measured the signal-to-noise ratio of the input  $\mathcal{R}_{S/N,\text{in}}$  and the signal-to-noise ratio of the output  $\mathcal{R}_{S/N,\text{out}}$  for the conjugate amplitude and phase quadratures, respectively (see, e.g., [33]). The variances of added noises in the output quadratures  $\langle n_{\text{out},x}^2 \rangle$  and  $\langle n_{\text{out},p}^2 \rangle$  then read as

$$\langle n_{\text{out},x}^2 \rangle = \frac{\mathcal{R}_{S/N,\text{in},x}}{\mathcal{R}_{S/N,\text{out},x}} - 1, \quad \langle n_{\text{out},p}^2 \rangle = \frac{\mathcal{R}_{S/N,\text{in},p}}{\mathcal{R}_{S/N,\text{out},p}} - 1. \quad (50)$$

The variances  $\langle n_{\text{cl},x}^2 \rangle$  and  $\langle n_{\text{cl},p}^2 \rangle$  of the noises added into the classical measurement outcomes were calculated from the measured transmittance  $T$  of the variable beam splitter. By construction, the device should exhibit identical transmittance for the amplitude and phase quadratures, and this was explicitly confirmed by measurement. We thus have

$$\nu_{\text{cl}} = \langle n_{\text{cl},x}^2 \rangle = \langle n_{\text{cl},p}^2 \rangle = \frac{1+T}{1-T}. \quad (51)$$

Simultaneously changing the transmittance  $T$  and the electronic gain  $G$  enabled us to adjust at will the degree of disturbance of the measured quantum state. The experimental results are summarized in Fig. 4. We get excellent agreement between theory and experiment and we conclude that the measurement apparatus operates at the fundamental limits imposed by quantum theory.

In our second experiment we demonstrated the MDM for a fixed optical gain. After analyzing our input state as in the previous experiment we connected the feed-forward loop and adjusted the appropriate electronic gain, which guaranteed the desired fixed optical gain. This means that for a particular beam splitter transmittance the feed-forward electronic gain will increase as the desired optical gain increases. If, in addition, the desired optical gain is less than the beam splitter transmittance then a deamplification of the optical signal is required, which was achieved by adding a  $\pi$  phase shift in the electronic feed-forward loop and by making use of destructive interference, which resulted in optical deamplifica-

tion. This particular operation is actually suboptimal meaning that the measurement outcomes lie outside the optimality window, which follows directly from the fact that in this case where  $g < \sqrt{T}$ , calculation of  $\nu_{\text{cl}}$  reveals that  $\nu_{\text{cl}} > (1+g^2)/|1-g^2|$ . Using a similar procedure as before we measured the first and second moments for the amplitude and phase quadrature of the output signal. Having measured the input and output states we then calculate all the necessary added noises by means of Eqs. (50) and (51).

We performed this kind of measurement for three fixed optical gains of  $g^2 = 0.5, 0.8, 1.3$  and the results are summarized in Fig. 5. Here we have to stress again that optimal MDMs with a fixed optical gain lie only within a specific region of the  $(\nu_{\text{cl}}, \nu_{\text{out}})$ -plane (gray shaded region in the figures). The boundaries of these regions depend solely on the optical gain and can be easily determined from Eqs. (14) and (15). For the optical gains considered here these optimality windows explicitly read as follows:

$$1 \leq \nu_{\text{cl}} \leq 3, \quad 1 \leq \nu_{\text{out}} \leq 3 \quad \text{for } g^2 = 0.5,$$

$$1 \leq \nu_{\text{cl}} \leq 9, \quad \frac{1}{4} \leq \nu_{\text{out}} \leq \frac{9}{4} \quad \text{for } g^2 = 0.8,$$

$$1 \leq \nu_{\text{cl}} \leq \frac{23}{3}, \quad \frac{3}{13} \leq \nu_{\text{out}} \leq \frac{23}{13} \quad \text{for } g^2 = 1.3.$$

The left-hand sides of these inequalities are dictated by the commutation relations (6) and cannot be overcome by any operation, i.e., the theoretical tradeoff in the figures never lies below or to the left of the optimality window. However, the tradeoff (13) lies to the right of the optimality window for sufficiently large noise  $\nu_{\text{cl}}$ . In this case the operation saturating the tradeoff is suboptimal and a better performance is obviously obtained by the operation corresponding to the minimum of the tradeoff, which also corresponds to the bottom right corner of the optimality window. Note that the only exception occurs in the unity gain regime ( $g=1$ ) demonstrated in [10] where the optimality window is not bounded from the right; i.e.,

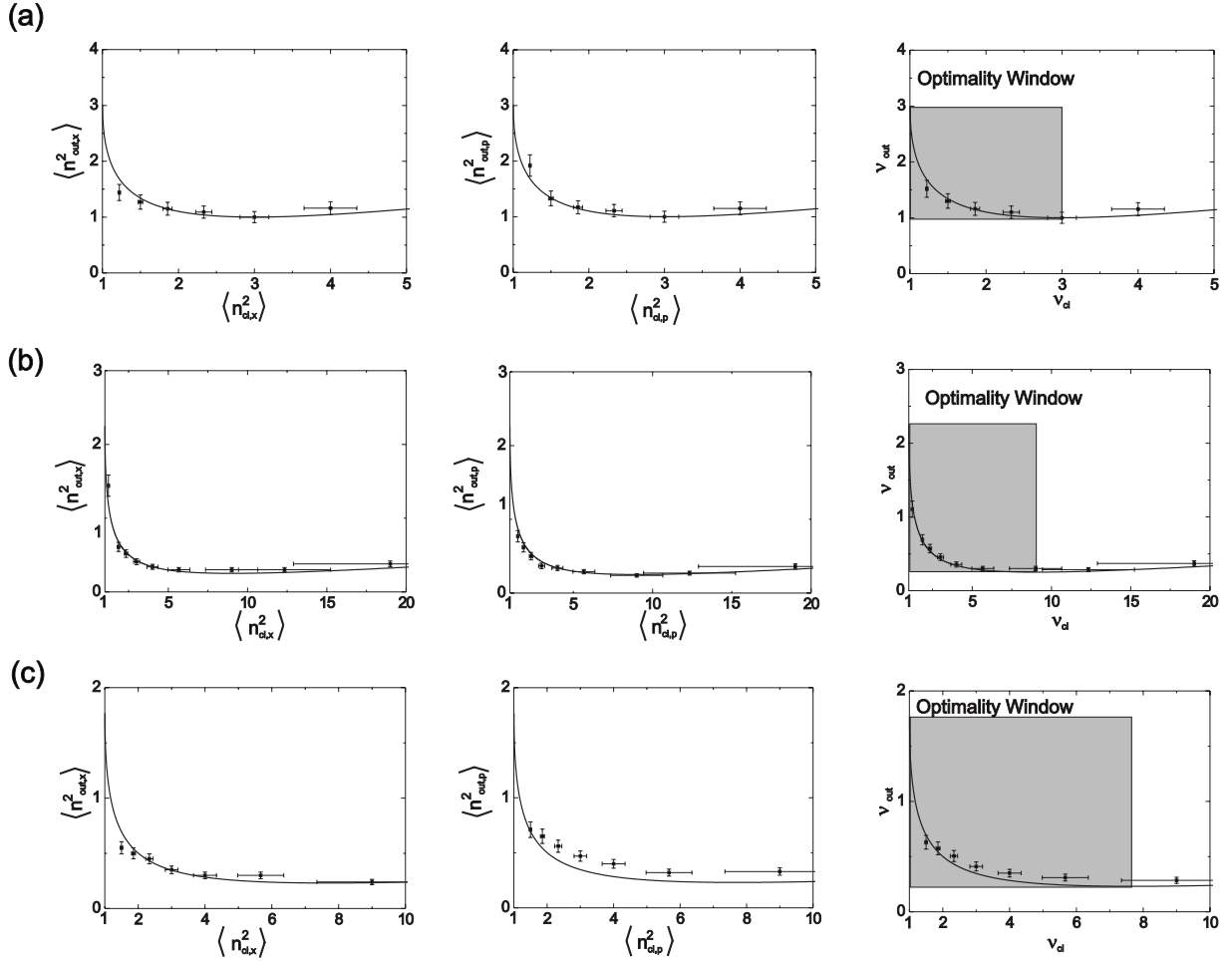


FIG. 5. Experimental results for MDM with fixed gains  $g^2=0.5$  (a),  $g^2=0.8$  (b), and  $g^2=1.3$  (c). Variances  $\langle n_{\text{out},x}^2 \rangle$  (left figure) and  $\langle n_{\text{out},p}^2 \rangle$  (middle figure) of the added noises in the amplitude and phase quadratures are plotted against the  $\langle n_{\text{cl},x}^2 \rangle$  and  $\langle n_{\text{cl},p}^2 \rangle$  characterizing the noise added into the outcomes of simultaneous measurement of amplitude and phase quadratures. We also make use of Eq. (7) to plot  $\nu_{\text{out}}$  against  $\nu_{\text{cl}}$  (right figure). The optimality windows (gray shaded regions) are determined by Eqs. (14) and (15). The solid line represents the theoretical tradeoff (13). The experimental data were obtained by taking into account the detection efficiency of 83% at the homodyne detector. The error bars in the  $x$  axis stem from the uncertainty in the measurement of the beam splitter transmission (2% deviation). The error bars in the  $y$  axis are caused by 0.1 dB relative measurement accuracy of the electronic spectrum analyzer and 0.1 dB deviation of the homodyning efficiency.

$$1 \leq \nu_{\text{cl}} \leq \infty, \quad 0 \leq \nu_{\text{out}} \leq 2. \quad (52)$$

Thus, since  $\nu_{\text{cl}} - \sqrt{\nu_{\text{cl}}^2 - 1} \leq 1$  for any  $\nu_{\text{cl}} \geq 1$  the optimal output noise  $\nu_{\text{out}}$  for  $g=1$  always satisfies the second inequality in Eq. (52) and therefore in the unity gain regime the tradeoff (13) never leaves the optimality window.

As can be seen in Fig. 5, the obtained experimental tradeoffs are in very good agreement with the theory, which shows that our measuring apparatus indeed realizes optimal nonunity gain Gaussian partial estimation of coherent states. In particular, the noises added to the phase and amplitude quadratures are practically the same, which confirms that the measurement procedure introduces isotropic phase-independent noise into the estimated state as well as the post-measurement state.

## VII. DISCUSSION AND CONCLUSIONS

Our experimental minimal disturbance measurement with fixed nonunity gain finds a direct application in the context

of optimal Gaussian individual attacks on coherent state quantum key distribution (QKD) with heterodyne detection and direct reconciliation [18]. The optimal tradeoff demonstrated by us determines the minimum added noise in the outcomes of simultaneous measurement of complementary quadratures a potential eavesdropper can reach for a Gaussian quantum channel with a fixed gain and a fixed phase-insensitive added noise. In the QKD terminology it means that the minimal-disturbance measurement provides an eavesdropper with maximum possible information that can be gained from an individual Gaussian attack in the heterodyne-based coherent state QKD protocol with direct reconciliation. Recently, the similar problem has been studied theoretically directly in the context of QKD [34] and another form of the above-mentioned tradeoff was found [Eq. (11) of Ref. [34]]. The proofs of optimality presented here, however, follow completely different strategies in comparison with those presented in [34] and more importantly

we saturate the optimal tradeoff between added noises experimentally.

In this paper we have extended the concept of the phase-insensitive MDM for coherent states to the nonunity gain regime. We have given a complete theoretical as well as experimental study of this MDM for two different scenarios. First, we have found the nonunity gain MDM assuming fixed optical gain. In the second scenario we considered MDM with optimized gain. We have shown that both MDMs can be realized by a scheme consisting of only linear optical elements and a feedforward and we implemented the scheme experimentally. We have experimentally reached theoretical limits in both scenarios. Our results give answer to a fundamental question of how much noise will be in the measurement outcomes from the nondestructive measurement of a coherent state provided that it is represented by a single-

mode Gaussian channel with a given optical gain and isotropic added noise. Our analysis could be also extended to phase-sensitive measurements such as the quantum non-demolition measurement of a single quadrature of light.

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